# **Stochastic Processes**



#### **Week 01 (version 1.1) Review of Probability Introduction to Stochastic Processes** Hamid R. Rabiee Fall 2023

# **Outline of Week 01 Lectures**

- History/Philosophy
- Random Variables
- Density/Distribution Functions
- Joint/Conditional Distributions
- Correlation
- Important Theorems
- •Introduction to Stochastic Processes

# **History & Philosophy**

- Started by gamblers' dispute!
- Probability as a game analyzer
- Formulated by B. Pascal and P. Fermet
- First Problem (1654) :
	- "Double Six" during 24 throws!
- First Book (1657):
	- •*Christian Huygens*, "*De Ratiociniis in Ludo Aleae", In German, 1657.*

- Rapid development during 18<sup>th</sup> Century
- Major Contributions:
	- J. Bernoulli (1654-1705)
	- •A. De Moivre (1667-1754)
- A renaissance: Generalizing the concepts from mathematical analysis of games to analyzing scientific and practical problems: P. Laplace (1749-1827)
- New approach first book:
	- •P. Laplace, "*Théorie Analytique des Probabilités*", In France, 1812.

- 19<sup>th</sup> century's developments:
	- •Theory of errors
	- •Actuarial mathematics
	- •Statistical mechanics
- Modern theory of probability (20<sup>th</sup> Century):
	- A. Kolmogorov : Axiomatic approach
- First modern book:
	- A. Kolmogorov, "Foundations of Probability Theory", Chelsea, New York, 1950.
- Other giants in the field:
	- Chebyshev and Markov

- Two major philosophies:
	- Frequentist Philosophy
		- •Observation is enough!
	- Bayesian Philosophy:
		- Observation is NOT enough
		- Prior knowledge is essential

#### **Frequentist philosophy**

- There exist fixed parameters like mean, $\theta$ .
- There is an underlying distribution from which samples are drawn
- Likelihood functions( $L(\theta)$ ) maximize parameter/data
- For Gaussian distribution the  $L(\theta)$  for the mean happens to be 1/N $\sum_i\!\mathsf{x}_\mathsf{i}$  or the average.

#### **Bayesian philosophy**

- Parameters are variable
- Variation of the parameter defined by the prior probability
- This is combined with sample data  $p(X/\theta)$  to update the posterior distribution  $p(\theta/X)$ .
- Mean of the posterior,  $p(\theta/X)$ , can be considered a point estimate of  $\theta$ .

#### • An Example:

- A coin is tossed 1000 times, yielding 800 heads and 200 tails. Let  $p = P$ (heads) be the bias of the coin. What is *p*?
- Bayesian Analysis
	- Our prior knowledge (believe):  $\pi(p)$ =1 (Uniform(0,1))
	- Our posterior knowledge:  $\pi(p|Observation) = p^{800}(1-p)^{200}$
- Frequentist Analysis
	- Answer is an estimator  $\hat{p}$  such that
		- Mean:  $E[\hat{p}] = 0.8$
		- Confidence Interval:  $P(0.774 \le \hat{p} \le 0.826) \ge 0.95$

Nowadays, Probability Theory is considered to [a part of Measure Theory!](http://www.cs.ucl.ac.uk/staff/D.Wischik/Talks/histprob.pdf)

- •Further reading:
	- http://www.leidenuniv.nl/fsw/verduin/stathi athist.htm
	- http://www.mrs.umn.edu/~sungurea/intros istory/indexhistory.shtml
	- www.cs.ucl.ac.uk/staff/D.Wischik/Talks/his b.pdf

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- •History/Philosophy
- •Random Variables
- •Density/Distribution Functions
- Joint/Conditional Distributions
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- •Important Theorems
- •Introduction to Stochastic Processes

## **Random Variables**

- •Probability Space
	- A triple of  $(\Omega, F, P)$ 
		- $\Omega$  represents a nonempty set, whose elements are sometimes known as outcomes or states of nature (Sample Space).
		- $\cdot$   $F$  represents a set, whose elements are called events. The events are subsets of  $\Omega$ *. F* should be a "Borel Field".
		- $\cdot$  *P* represents the probability measure.
- Fact:  $P(\Omega) = 1$

#### **Random Variables (Cont'd)**

- Random Variable (RV) is a "function" ("mapping") from a set of possible outcomes of the experiment to an interval of real (complex) numbers.
- In other words:



# **Random Variables (Cont'd)**

- •Example I:
	- •Mapping faces of a dice to the first six natural numbers.
- •Example II:
	- •Mapping height of a man to the real interval (0,3] (meter or something else).
- •Example III:
	- •Mapping success in an exam to the discrete interval [0,20] by quantum 0.1.

## **Random Variables (Cont'd)**

- •Random Variables
	- •Discrete
		- •Dice, Coin, Grade of a course, etc.
	- •Continuous
		- •Temperature, Humidity, Length, etc.
- •Random Variables
	- •Real
	- •Complex

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## **Density/Distribution Functions**

- Probability Mass Function (PMF)
	- Discrete random variables
	- Summation of impulses
	- The magnitude of each impulse represents the probability of occurrence of the outcome
- Example I:
	- Rolling a fair dice



- Cumulative Distribution Function (CDF)
	- Both Continuous and Discrete
	- Could be defined as the integration of PDF

$$
CDF(x) = F_X(x) = P(X \le x)
$$
  

$$
F_X(x) = \int_{-\infty}^{x} f_X(x) dx
$$



- •Some CDF properties
	- •Non-decreasing
	- •Right Continuous
	- $F(-infinity) = 0$
	- $\cdot$  F(infinity) = 1

• Probability Density Function (PDF)

- Continuous random variables
- The probability of occurrence of  $x_0 \in \left(x \frac{dx}{2}, x + \frac{dx}{2}\right)$ will be  $P(x)dx$



 $P(X)$ 

- Some famous masses and densities:
	- Uniform Density

$$
f(x) = \frac{1}{a} (U(\text{end}) - U(\text{begin}))
$$

$$
\frac{1}{a} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0
$$

à.

• Gaussian (Normal) Density



**• Binomial Density** 

$$
f(n) = {N \choose n} (1-p)^n \cdot p^{N-n}
$$

• Poisson Density

$$
f(x) = e^{-\lambda} \frac{\lambda^x}{\Gamma(x+1)}
$$
  
Note:  $x \in \aleph \implies \Gamma(x+1) = x!$ 





#### • Important Fact:

For Sufficient ly large  $N:$   $\binom{N}{n}$   $(1-p)^{N-n}$   $\cdot p^n \approx e^{-N} \cdot p \frac{(N \cdot p)^n}{n!}$ 

• Exponential Density



- **. Expected Value** 
	- . The most likelihood value:

$$
E[X] = \int_{-\infty}^{\infty} x \cdot f_X(x) dx
$$

• Linear Operator:

$$
E[a.X+b] = a.E[X]+b
$$

- Function of a random variable:
	- Expectation

$$
E[g(X)] = \int_{-\infty}^{\infty} g(x) f_X(x) dx
$$

•PDF of a function of random variables:

- Assume RV "Y" such that  $Y = g(X)$
- The inverse equation  $X = g^{-1}(Y)$  may have more than one solution called  $X_1, X_2, ..., X_n$
- •PDF of "Y" can be obtained from PDF of "X" as follows:

$$
f_Y(y) = \sum_{i=1}^n \frac{f_X(x_i)}{dx} g(x) \Big|_{x=x_i}
$$

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# **Joint/Conditional Distributions**

- Joint Probability Functions
	- Density  $F_{X,Y}(x,y) = P(X \le x \text{ and } Y \le y)$
	- Distribution

$$
=\int_{-\infty}^{x} \int_{-\infty}^{y} f_{X,Y}(x,y)dydx
$$

#### • Example I:

• In a rolling fair dice experiment represent the outcome as a 3-bit digital number "xyz".

$$
f_{X,Y}(x, y) = \begin{cases} 1/6 & x = 0; y = 0 & 1 \rightarrow 001 \\ 1/3 & x = 0; y = 1 & 2 \rightarrow 010 \\ 1/3 & x = 1; y = 0 & 3 \rightarrow 011 \\ 1/6 & x = 1; y = 1 & 5 \rightarrow 101 \\ 0 & O.W. & 6 \rightarrow 110 \end{cases}
$$

- •Example II:
	- •Two normal random variables

$$
f_{X,Y}(x,y) = \frac{1}{2\pi \sigma_x \sigma_y \sqrt{1-r^2}} e^{-\left(\frac{1}{2(1-r^2)} \left(\frac{(x-\mu_x)^2}{\sigma_x^2} + \frac{(y-\mu_y)^2}{\sigma_y^2} - \frac{2r(x-\mu_x)(y-\mu_y)}{\sigma_x \sigma_y}\right)\right)}
$$

•What is "r" ?

• Independent Events (Strong Axiom)

$$
f_{X,Y}(x,y) = f_X(x) \cdot f_Y(y)
$$

• Obtaining one variable density functions:

$$
f_X(x) = \int_{-\infty}^{\infty} f_{X,Y}(x, y) dy
$$

$$
f_Y(y) = \int_{-\infty}^{\infty} f_{X,Y}(x, y) dx
$$

• Distribution functions can be obtained just from the density functions. (How?)

- Conditional Density Function:
	- Probability of occurrence of an event if another event is observed (we know what " $Y$ " is).

$$
f_{X|Y}(x|y) = \frac{f_{X,Y}(x,y)}{f_Y(y)}
$$

• Bayes' Rule:

$$
f_{X|Y}(x|y) = \frac{f_{Y|X}(y|x) f_X(x)}{\int_{-\infty}^{\infty} f_{Y|X}(y|x) f_X(x) dx}
$$

- •Example I:
	- •Rolling a fair dice:
		- •X : the outcome is an even number
		- •Y : the outcome is a prime number

$$
P(X|Y) = \frac{P(X,Y)}{P(Y)} = \frac{\frac{1}{6}}{\frac{1}{2}} = \frac{1}{3}
$$

- •Example II:
	- Joint normal (Gaussian) random variables:

$$
f_{X|Y}(x|y) = \frac{1}{\sqrt{2\pi} \cdot \sigma_x \cdot \sqrt{1-r^2}} e^{-\left(\frac{1}{2(1-r^2)}\left(\frac{x-\mu_x}{\sigma_x} - r \times \frac{y-\mu_y}{\sigma_y}\right)^2\right)}
$$

• Conditional Distribution Function:

$$
F_{X|Y}(x|y) = P(X \le x \text{ while } Y = y)
$$
  
= 
$$
\int_{-\infty}^{x} f_{X|Y}(x|y) dx
$$
  
= 
$$
\frac{\int_{-\infty}^{x} f_{X,Y}(t, y) dt}{\int_{-\infty}^{x} f_{X,Y}(t, y) dt}
$$

• Note that "y" is a constant during the integration.

• Independent Random Variables:

$$
f_{X|Y}(x|y) = \frac{f_{X,Y}(x,y)}{f_Y(y)}
$$

$$
= \frac{f_X(x).f_Y(y)}{f_Y(y)}
$$

$$
= f_X(x)
$$

• Remember! Independency is NOT heuristic.

• PDF of a functions of joint random variables

- Assume that  $(U,V) = g(X,Y)$
- The inverse equation set  $(X,Y) = g^{-1}(U,V)$ has a set of solutions  $(X_1, Y_1), (X_2, Y_2), ..., (X_n, Y_n)$
- Define Jacobean matrix as follows:

$$
\boldsymbol{J} = \begin{bmatrix} \frac{\partial}{\partial X} U & \frac{\partial}{\partial X} V \\ \frac{\partial}{\partial X} U & \frac{\partial}{\partial Y} V \end{bmatrix}
$$

• The joint PDF will be:

$$
f_{U,V}(u,v) = \sum_{i=1}^{n} \frac{f_{X,Y}(x_i, y_i)}{absolute determinant(J|_{(x,y)=(x_i,y_i)})}
$$

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# **Correlation**

- •Knowing about a random variable "X", how much information will we gain about the other random variable "Y" ?
- Shows linear similarity
- •More formal:  $Crr(X, Y) = E[X, Y]$

•Covariance is normalized correlation  $[Cov(X, Y) = E[(X - \mu_Y)](Y - \mu_Y)] = E[X,Y] - \mu_Y \mu_Y$ 

# **Correlation (cont'd)**

#### •Variance

• Covariance of a random variable with itself

$$
Var(X) = \sigma_X^2 = E[(X - \mu_X)^2]
$$

•Relation between correlation and covariance

$$
E[X^2] = \sigma_X^2 + \mu_X^2
$$

#### •Standard Deviation

•Square root of variance

# **Correlation (cont'd)**

#### • Moments

 $\cdot$  n<sup>th</sup> order moment of a random variable "X" is the expected value of " $X^{n}$ "

$$
\boldsymbol{M}_n = E\Bigl(X^n\Bigr)
$$

• Normalized form

$$
M_n = E\Big((X - \mu_X)^n\Big)
$$

- Mean is the first moment
- Variance is second moment added by the square of the mean

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#### **Important Theorems**

- **Central limit theorem (CLT)**
	- Consider i.i.d. (Independent Identically Distributed) RVs " $X_k$ " with finite variances

• Let 
$$
S_n = \sum_{i=1}^n a_n \cdot X_n
$$

- Then PDF of " $S_n$ " converges to a normal distribution as *n* increases, regardless of the initial density of RVs.
- Exception: Cauchy Distribution (Why?)

- Law of Large Numbers (Weak)
	- $\bullet$  For i.i.d. RVs " $X_k$ "

$$
\forall_{\varepsilon>0} \quad \lim_{n\to\infty} \quad \Pr\left\{ \left| \frac{\sum_{i=1}^{n} X_i}{n} - \mu_X \right| > \varepsilon \right\} = 0
$$

- **. Law of Large Numbers (Strong)** 
	- $\bullet$  For i.i.d. RVs " $X_k$ "

$$
\Pr\left\{\lim_{n\to\infty}\frac{\sum_{i=1}^{n}X_i}{n}=\mu_X\right\}=1
$$

• Why this definition is stronger than the weak law of large numbers?

- **Chebyshev's Inequality**
	- Let "X" be a nonnegative RV
	- Let "c" be a positive number, then:  $Pr{X > c} \le -E[X]$ *c*  $Pr{X > c} \leq \frac{1}{2}$
	- The term Chebyshev's inequality may also refer<br>to Markov's inequality, especially in the context of<br>analysis. They are closely related, and some authors refer to Markov's inequality as "Chebyshev's First<br>Inequality,"
- Another form:

$$
\Pr\left\{|X - \mu_X| > \varepsilon\right\} \le \frac{\sigma_X^2}{\varepsilon^2}
$$

• This could also be rewritten for negative RVs.

- **. Schwarz Inequality** 
	- For two RVs "X" and "Y" with finite second moments:

$$
\mathbf{E}[X.Y]^2 \le \mathbf{E}[X^2].\mathbf{E}[Y^2]
$$

• Equality holds in case of linear dependency.

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- Let  $\xi$  denote the random outcome of an experiment.
- To every such outcome suppose a function  $X(t,\xi)$  is assigned.  $X(t,\xi)$
- The collection of such functions form a stochastic process.
- The set of  $\{\xi_k\}$  and the  $x(t,\xi_2)$ time index *t* can be continuous or discrete (countably infinite or finite).
- For fixed  $\xi_i \in S$  (the set of all experimental outcomes),  $X(t,\xi)$  is a specific time function.



- For fixed *t*,  $X_1 = X(t_1, \xi)$  is a random variable.
- The ensemble of all such realizations  $X(t,\xi)$  over time represents the stochastic process *X*(*t*).



#### • Examples:

- Let  $X(t) = a \cos(\omega_0 t + \varphi),$ where  $\varphi$  is a uniformly distributed random variable in  $(0, 2\pi)$ , represents a stochastic process.
- Stochastic processes are everywhere:
	- stock market fluctuations
	- various queuing systems
	- Earthquake Signals
	- 1-D Audios
	- 2-D Images
	- 3-D Videos

#### • Example 1:

The Random Process (RP)  $X(t)$  is defined as:  $X(t) = At + b$ , b is a constant, A is a Gaussian rv,  $t > 0$ Find  $f_X(x,t)$  :

$$
f_A(a) = \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{a^2}{2}\right) = N(0, 1)
$$

$$
f_X(x, t) = \frac{f_A(a)}{\left|\frac{dx}{dA}\right|}
$$

$$
A = \frac{X(t) - b}{t} \qquad \left|\frac{dX}{dA}\right| = t, \qquad a = \frac{x - b}{t}
$$

$$
f_X(x, t) = \frac{1}{t} f_A(a) = \frac{1}{\sqrt{2\pi t}} \exp\left(-\frac{a^2}{2}\right) = \frac{1}{\sqrt{2\pi t}} \exp\left(-\frac{(x - b)^2}{2t^2}\right)
$$

#### • Example 1:

The Random Process (RP)  $X(t)$  is defined as:  $X(t) = At + b$ , b is a constant, A is a Gaussian rv,  $t > 0$ What is mean and variance of  $X(t)$ ?

#### • Example 1 continued:

Mean of  $X(t)$ :  $X(t) = At + b$ , A is  $N(0,1)$  $E[X(t)] = E[At + b] = E[A]t + E[b] = 0 \times t + b = b$ 

Variance of 
$$
X(t)
$$
:  
\n $X(t)2 = A^2t^2 + b^2 + 2Abt$   
\n $E[X(t)2] = E[A^2t^2 + b^2 + 2Abt] = E[A^2]t^2 + E[b^2]$   
\n $+ E[A] 2bt = 1 * t^2 + b^2 + 0 * 2bt$ 

$$
E[X(t)^{2}] = t^{2} + b^{2}
$$
  
 
$$
Var(X[t]) = E[X(t)2] - E[X(t)]2 = t^{2} + b^{2} - b^{2} = t^{2}
$$

**Note**: The mean of X(t) is constant but its variance is a function of time time t.



c)  $Var[X(t)] = ?$ 

#### Example 2 continued:  $X(t) = A \cos(w_0 t + \theta) = X_t(\theta)$

$$
f_X(x,t) = \sum_i \frac{f_\theta(\theta_i)}{\left|\frac{dX_t}{d\theta_i}\right|} = \frac{1}{2\pi} \frac{1[0 < \theta_i \le 2\pi]}{\left|\frac{dX_t}{d\theta_i}\right|}
$$

 $A\cos(w_0 t + \theta_i) = x \rightarrow$  has exactly 2 answers in (0, 2 $\pi$ )

$$
\left| \frac{dX_t}{d\theta_i} \right| = |-A \sin(w_0 t + \theta_i)| = \sqrt{A^2 - X_t^2}
$$
  
\n
$$
\rightarrow f_X(x, t) = \frac{2}{2\pi} \frac{1}{\sqrt{A^2 - x^2}} = \frac{1}{\pi \sqrt{A^2 - x^2}}
$$
 |X| \le A

#### Example 2 continued:

 $X(t) = A \cos(w_0 t + \theta) = X_t(\theta)$ 

$$
E[X(t)] = E[A\cos(w_0 t + \theta)] = A \int_0^{2\pi} \cos(w_0 t + \theta) \frac{1}{2\pi} d\theta = 0
$$

 $V[X(t)] = E[X(t)^{2}] - E[X(t)]^{2} = E[(A \cos(w_{0}t + \theta))^{2}]$ 

$$
= A^2 \int_0^{2\pi} \cos^2(w_0 t + \theta) \frac{1}{2\pi} d\theta
$$

$$
= \frac{A^2}{2\pi} \int_0^{2\pi} \frac{1}{2} (1 + \cos(2w_0 t + 2\theta)) d\theta = \frac{A^2}{2\pi} \int_0^{2\pi} \frac{1}{2} d\theta = \frac{A^2}{2}
$$

**Note**: The mean and variance of X(t) are constants in this example.

#### **Introduction to Stochastic Processes Stationary Processes**



#### **Next Week:**

#### **Stochastic Processes Stationary Stochastic Processes**

**Have a good day!**